

PRESENTATION

This project tries on an automatic system of watering using a called programmable robot C20 of the mark Sysmac, an electro valve and the necessary material for this project, as for example pipe and a drum of water.

This project will be thought for the Classroom T1 of technology of the Institute of the Cabin, in the one that in this classroom the six gavels are placed those that he/she is gone he/she is necessary to give a portion of water each 99s with that that this thought that the robot opens up and close every day. This function will also carry out it an electro valve.

The six gavels are each one from the other one to a distance 2 meters, and to a height 3,30 meters.

This robot also has the possibility to connect to the some sensor type to which has the function of measuring some variable type as you/he/she can be the humidity, the light, etc.

But in this project not this thought to make that, alone to put a robot, a drum that provides water and an electro valve.